



**JULIO 1, 2024 POR MICROLOG**

# ROBOT NADADOR

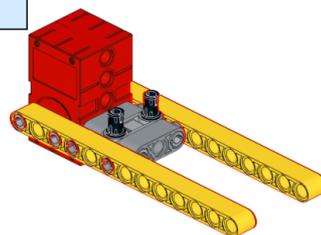
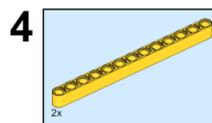
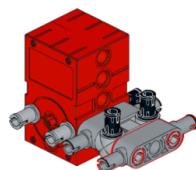
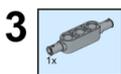
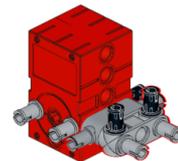
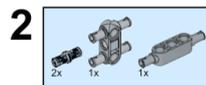
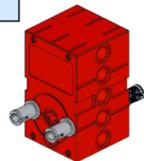
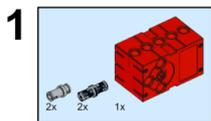
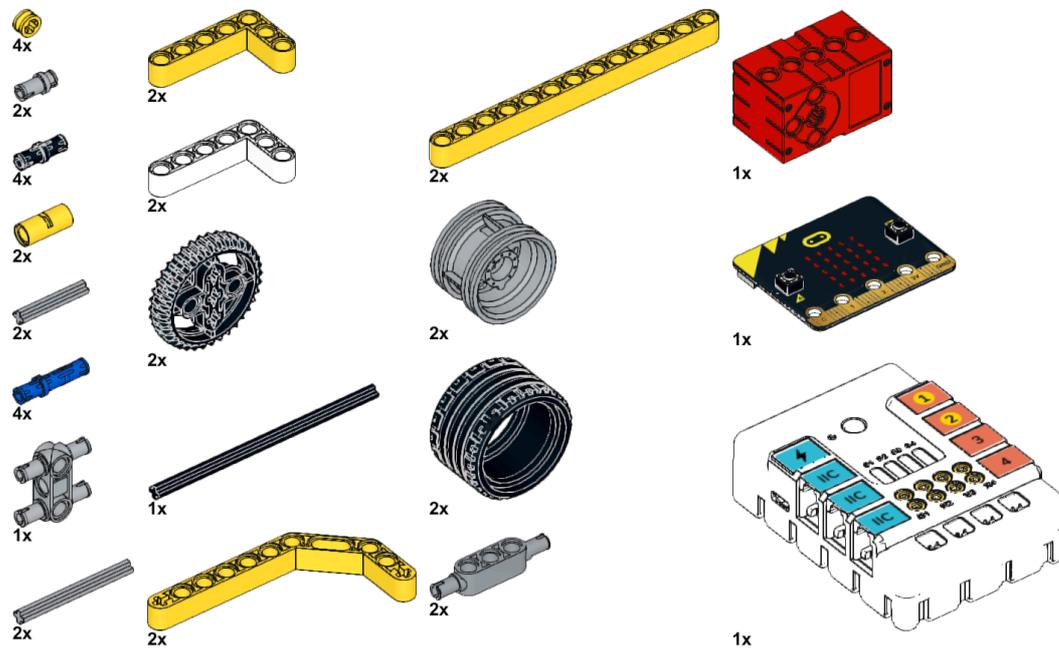
Construye un robot que imita los movimientos de un

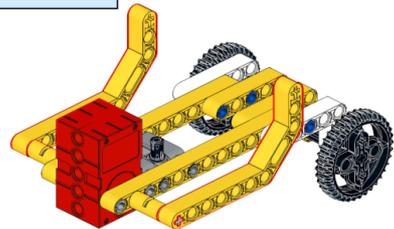
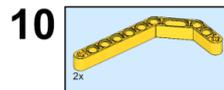
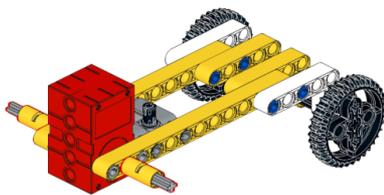
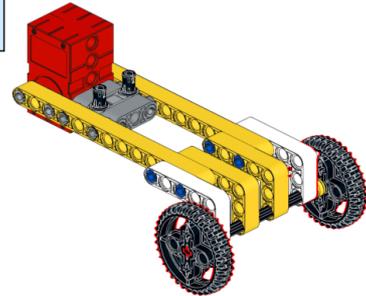
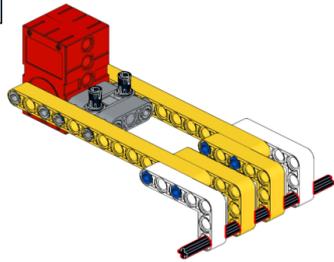
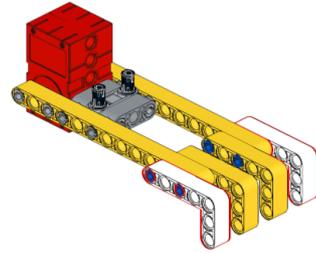
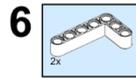
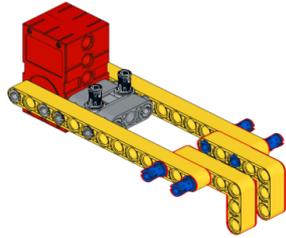
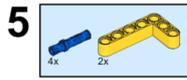


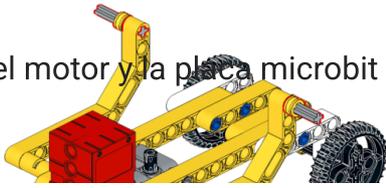
## LISTA DE MATERIALES:

- Módulo de conexiones Nezha
- Placa Micro:bit

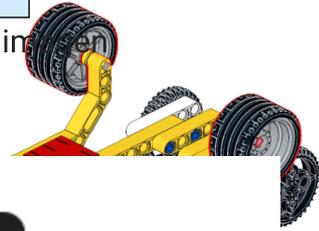
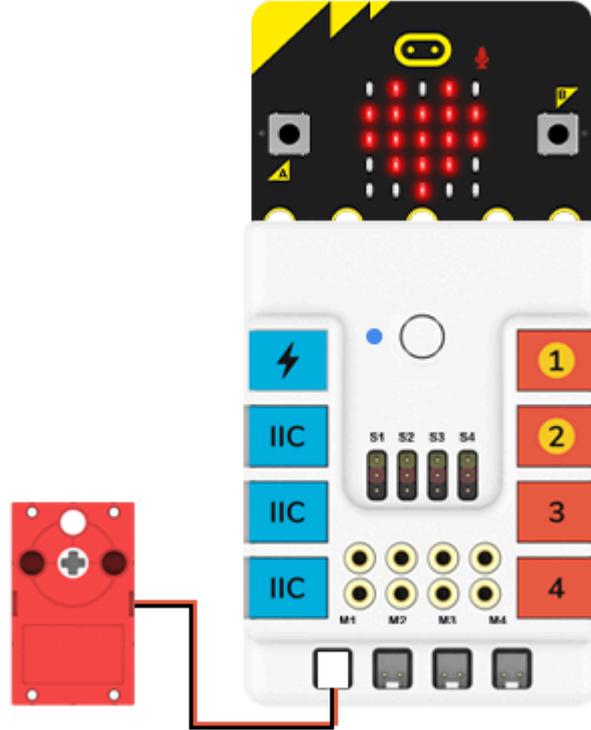
- 1 Motor
- Piezas Lego





**11** CIRCUNTO DE CONEXIONES:**12**

Conectar el motor y la placa microbit como se muestra en la imagen.

**13****PROGRAMACIÓN:**

```
on button A pressed
  show icon [grid icon]
  Set motor M1 speed to 100 %
```

```
on button B pressed
  Stop motor M1
  show icon [grid icon]
```

NEZHA V2