



**JULIO 1, 2024 POR MICROLOG**

# ROBOT LEVANTADOR DE PESO

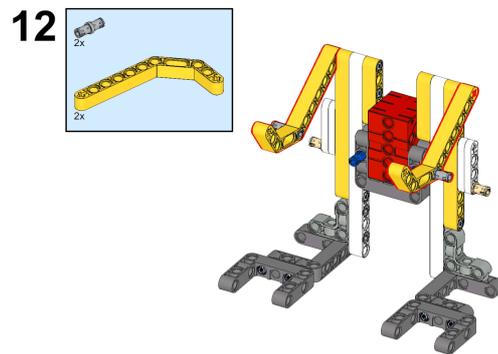
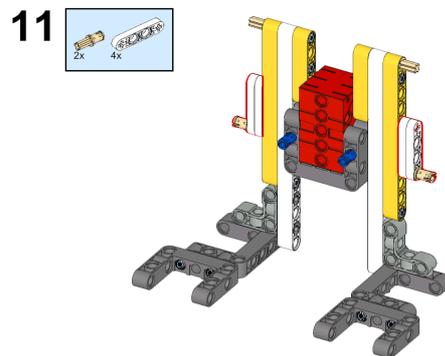
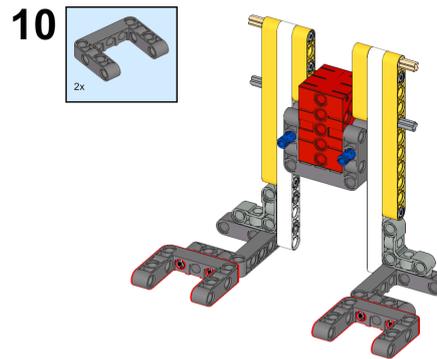
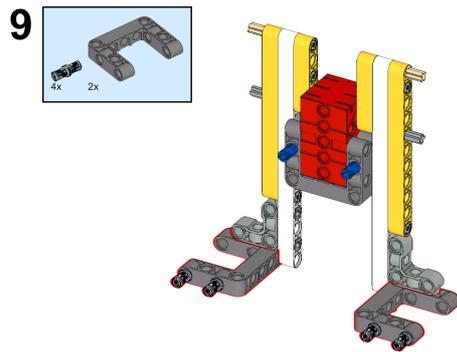
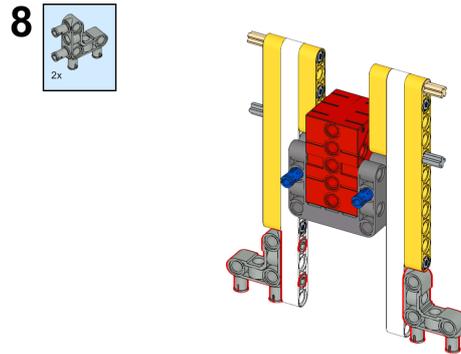
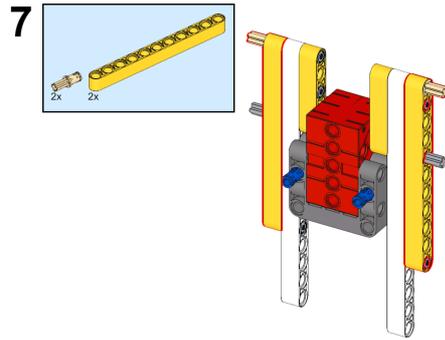
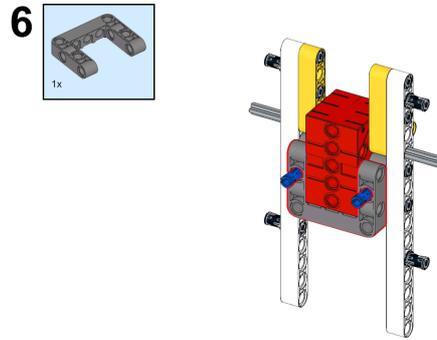
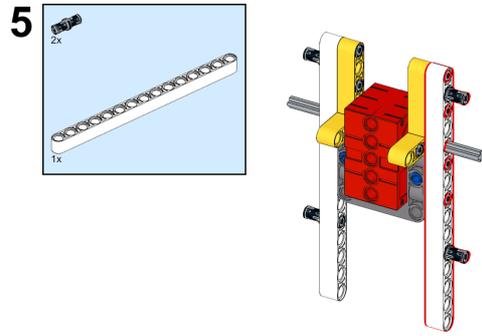
## OBJETIVO:

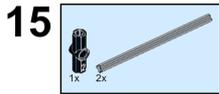
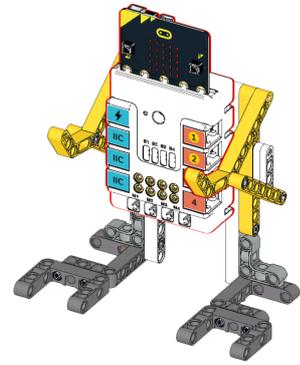
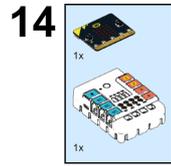
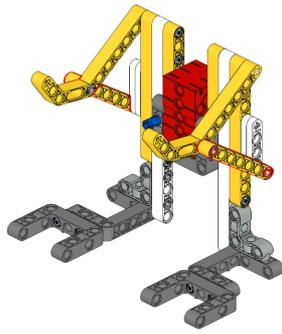
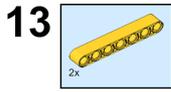
Construye un robot que imita el movimiento de un levantador de pesas.



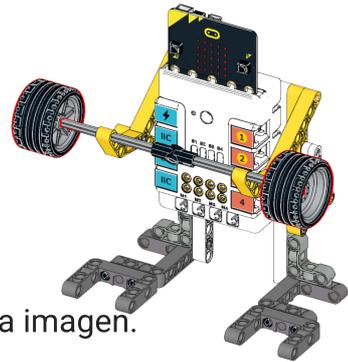
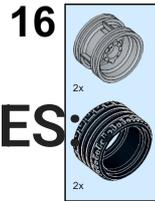
## LISTA DE MATERIALES:



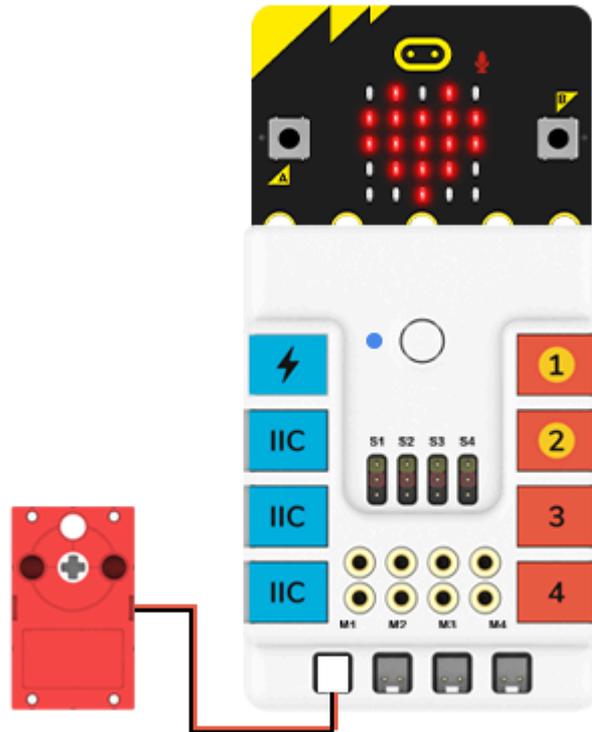




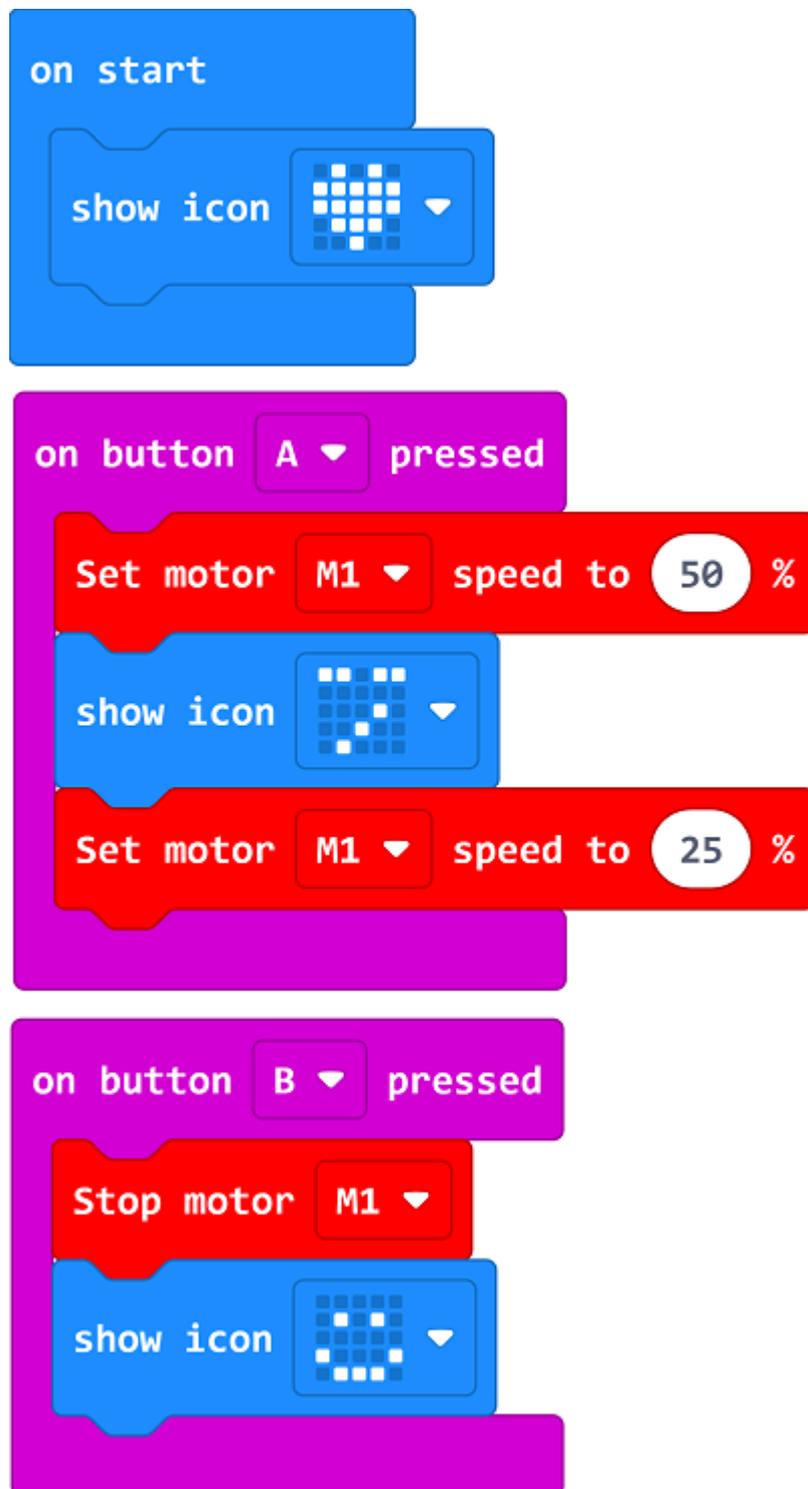
# CIRCUITO DE CONEXIONES



Conecta el motor y la placa microbit como se muestra en la imagen.



# PROGRAMACIÓN:



➤ **NEZHA V2**