



**JULIO 1, 2024 POR MICROLOG**

# ROBOT GIMNASTA

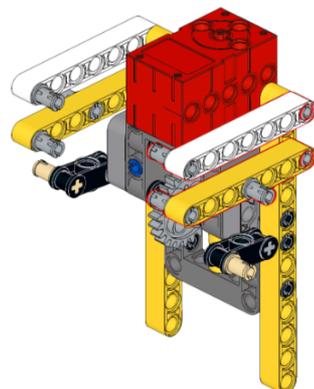
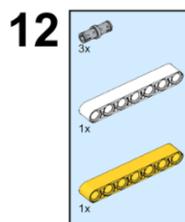
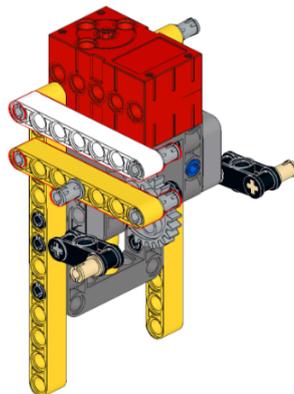
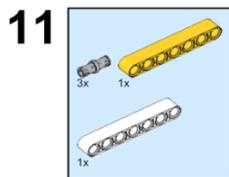
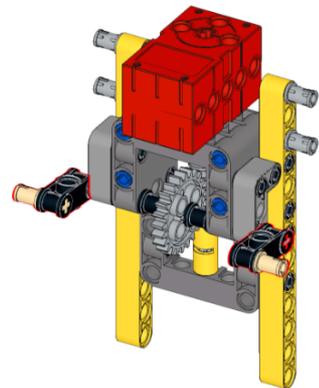
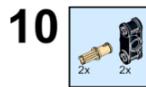
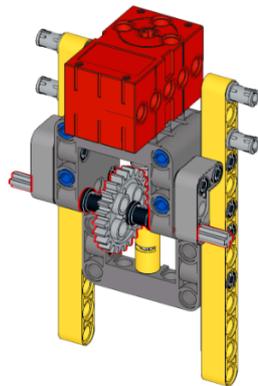
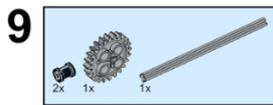
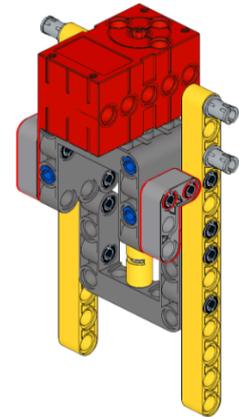
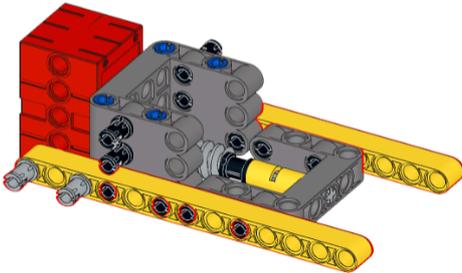
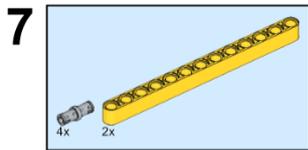
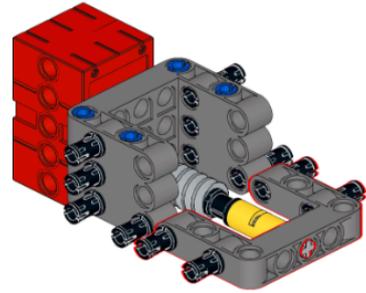
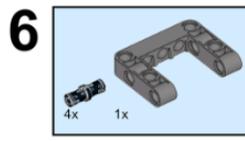
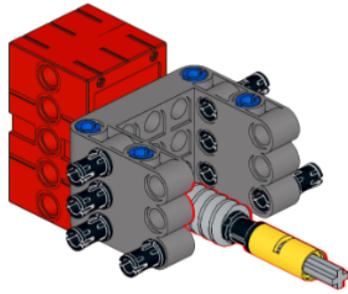
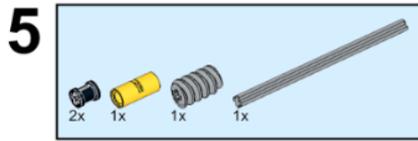
Construye un robot sujeto a una barra horizontal, capaz de elevarse.

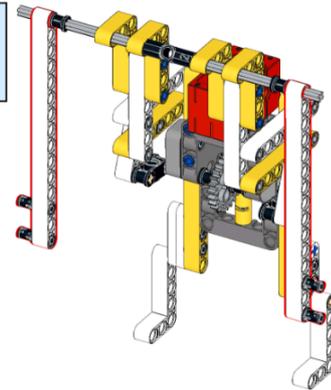
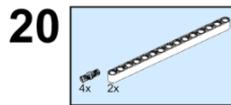
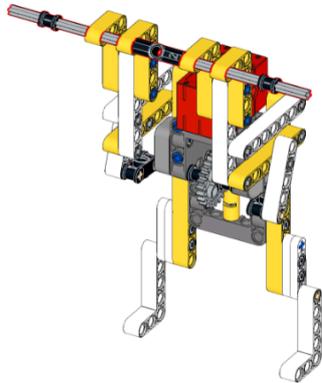
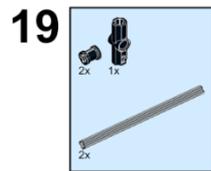
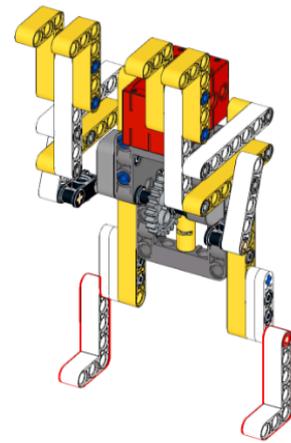
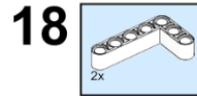
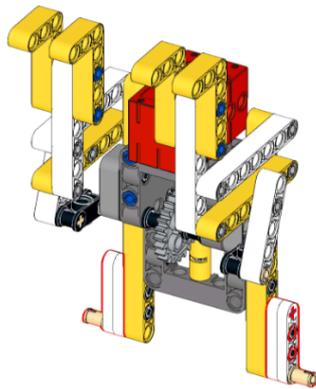
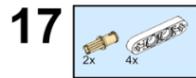
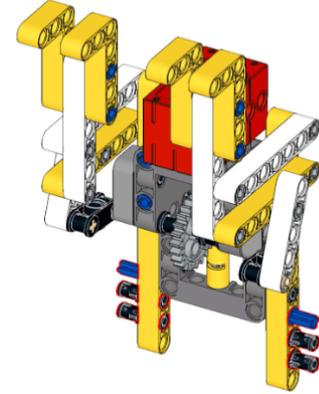
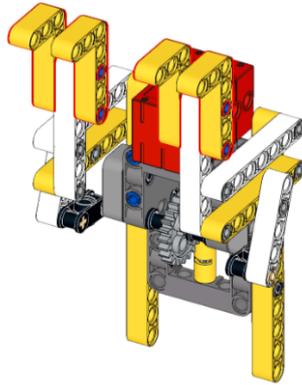
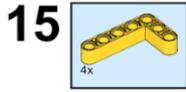
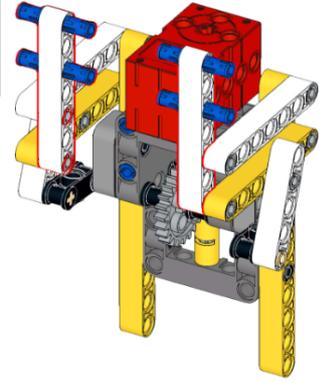
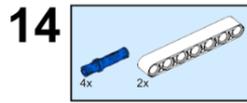
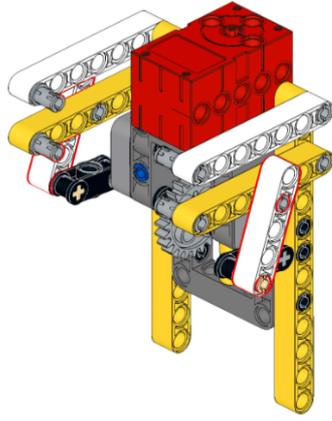
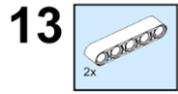


LISTA DE MATERIALES:

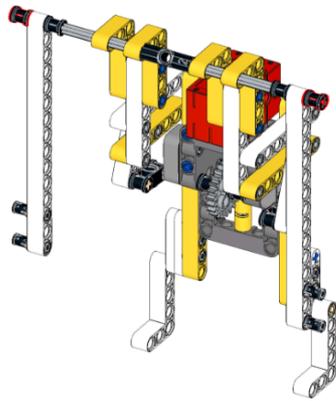
- Módulo de conexiones Nezha
- Placa Micro:bit



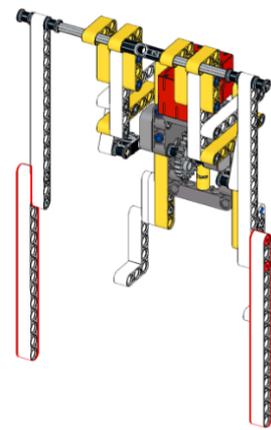
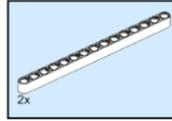




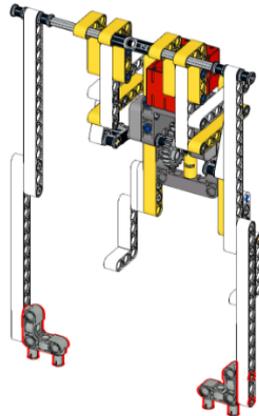
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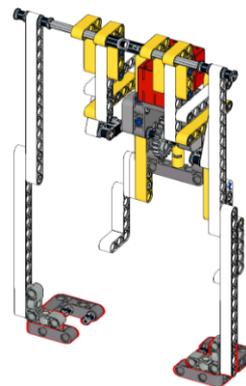
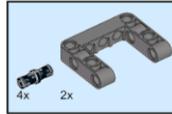
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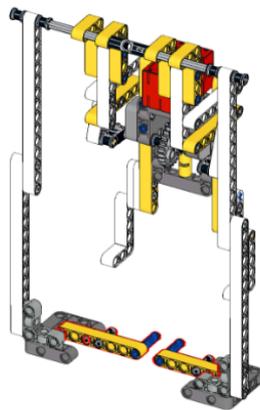
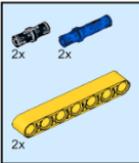
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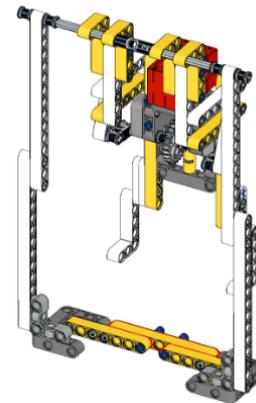
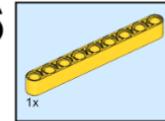
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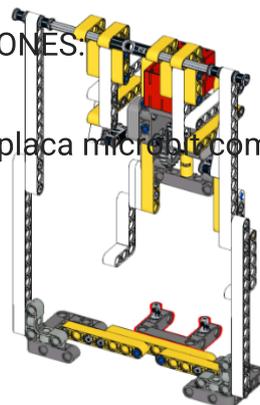
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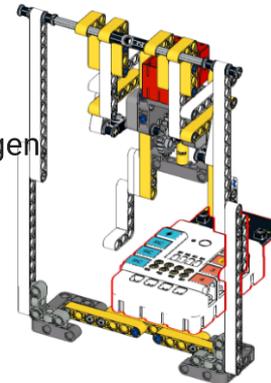
CIRCUITO DE CONEXIONES.



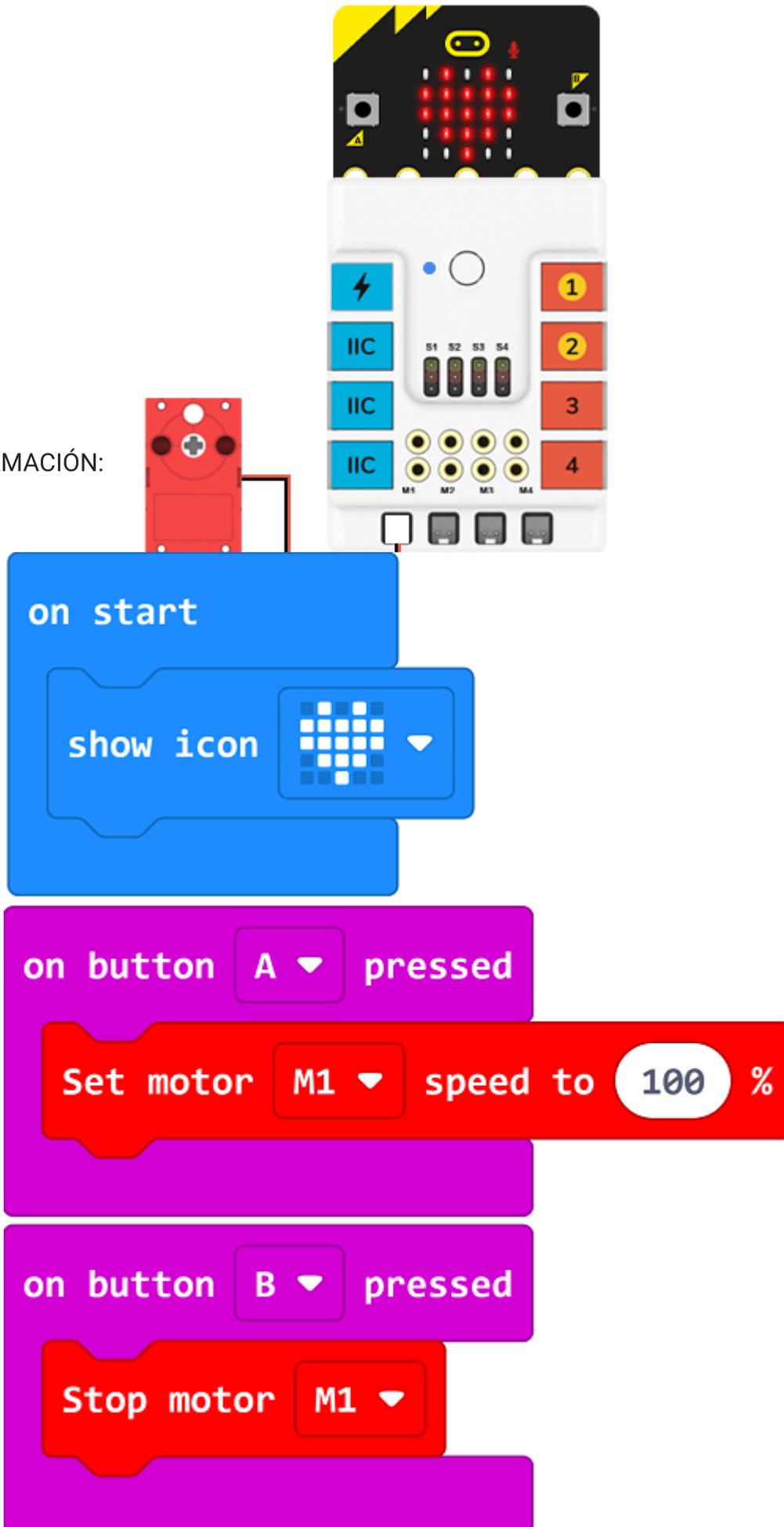
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Conecta el motor y la placa micro:bit como se muestra en la imagen.



PROGRAMACIÓN:



 **NEZHA V2**