



JULIO 1, 2024 POR MICROLOG

ROBOT ESCORPIÓN

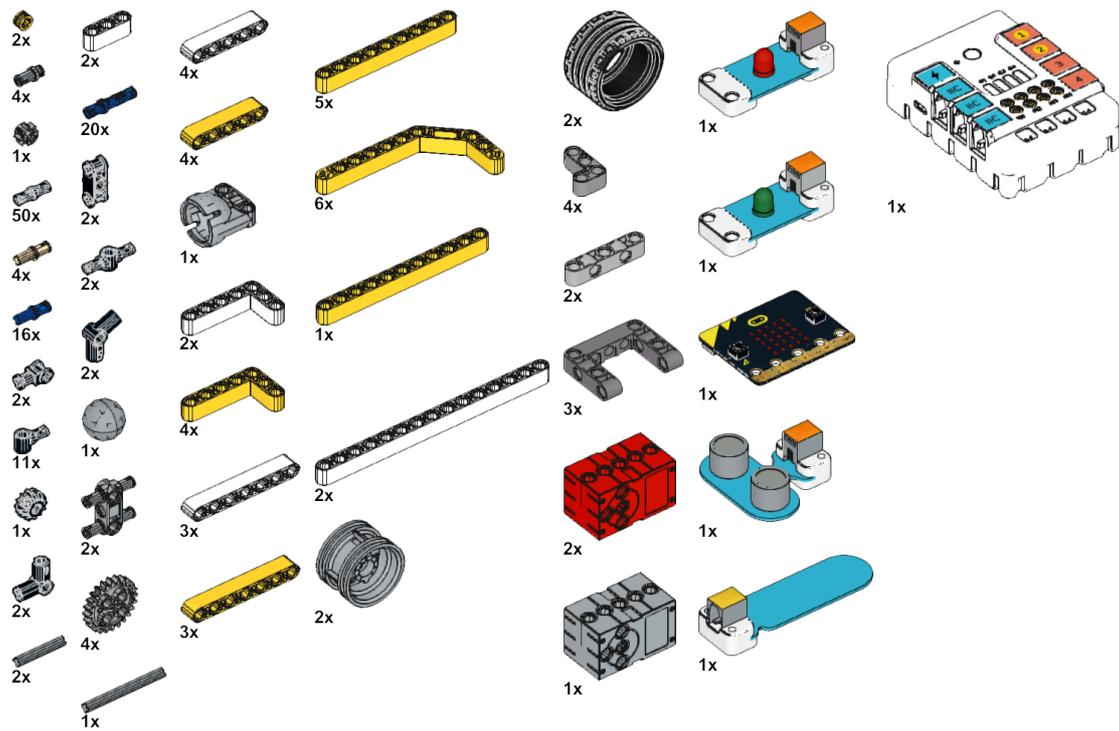
OBJETIVO:

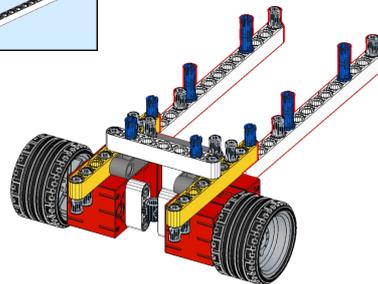
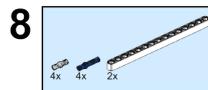
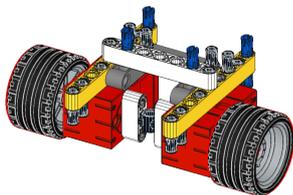
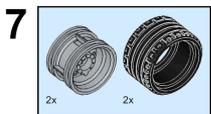
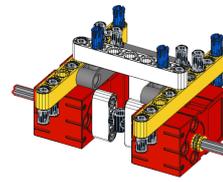
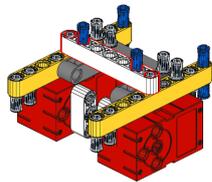
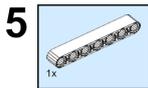
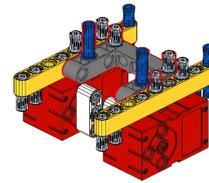
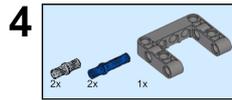
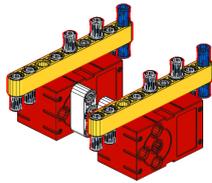
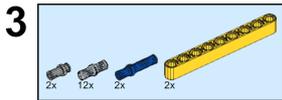
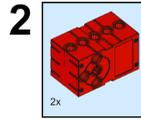
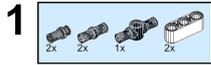
Construir un robot que al notar el contacto en su cola avance hasta localizar un objeto. al llegar al objeto, para y mueve sus pinzas.

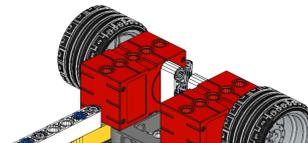
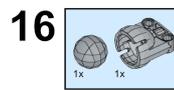
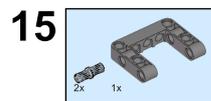
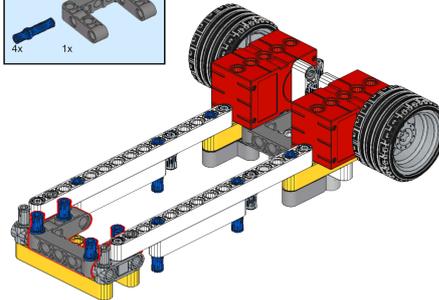
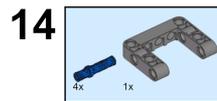
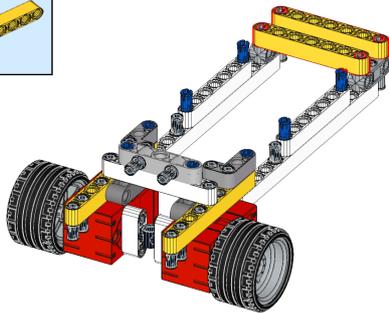
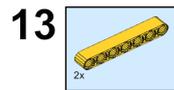
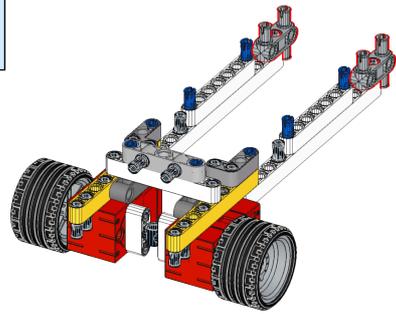
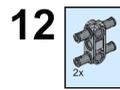
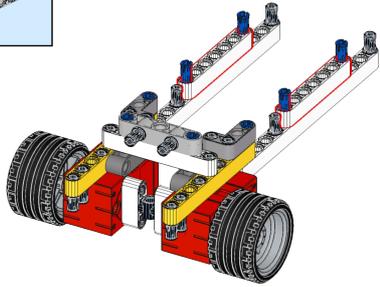
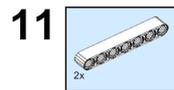
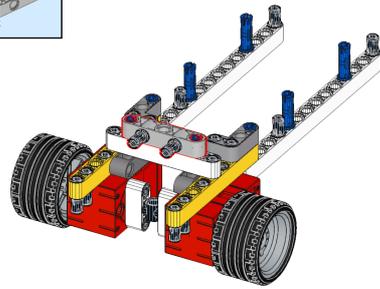
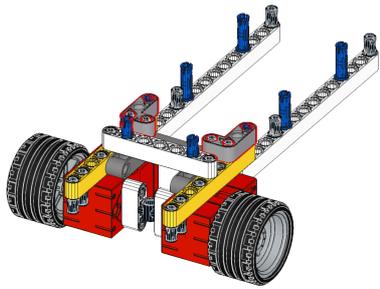


LISTA DE MATERIALES:

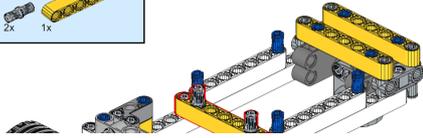
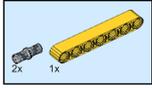
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- Placa Micro:bit
- 2 Motores
- Sensor de humedad
- Led rojo
- Led verde
- Sensor ultrasonido



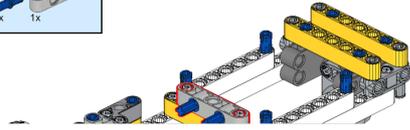
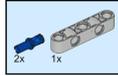




17



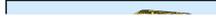
18



19



20



CIRCUITO DE CONEXIONES:

PROGRAMACIÓN:

 **NEZHA V2**