



JULIO 1, 2024 POR MICROLOG

ROBOT DIBUJANTE

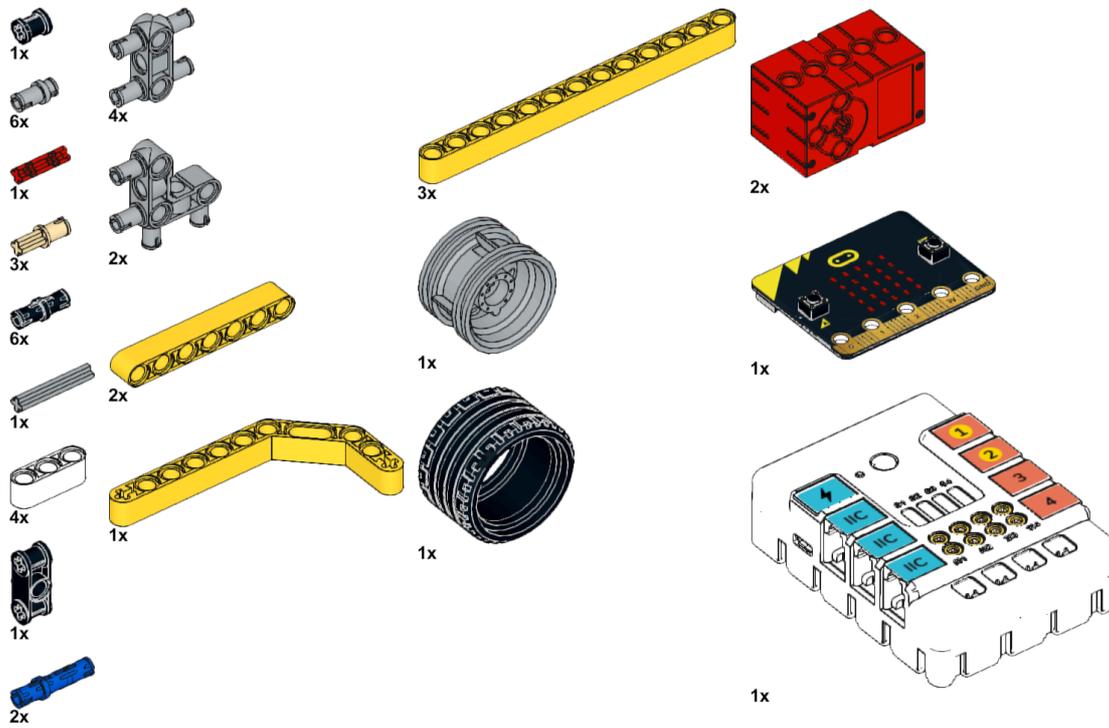
OBJETIVO:

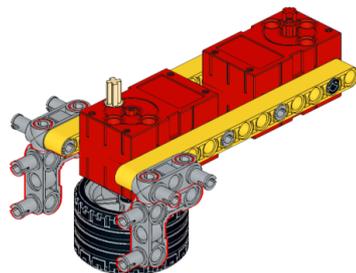
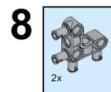
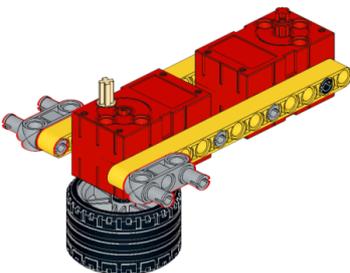
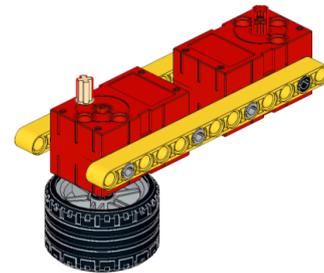
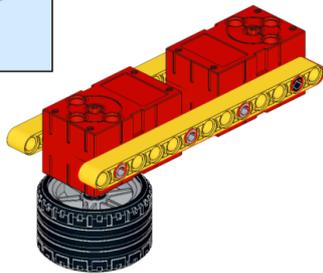
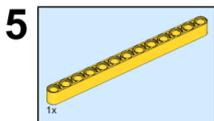
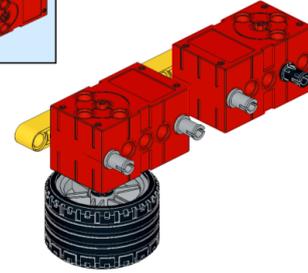
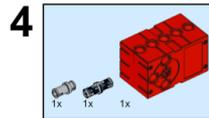
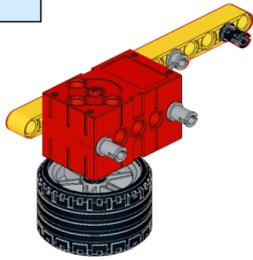
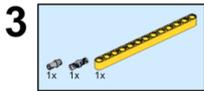
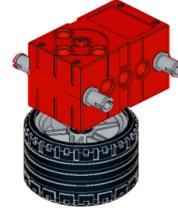
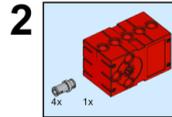
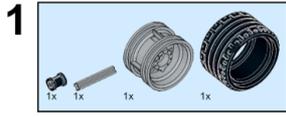
Construye un robot capaz de dibujar figuras basadas en circunferencias.

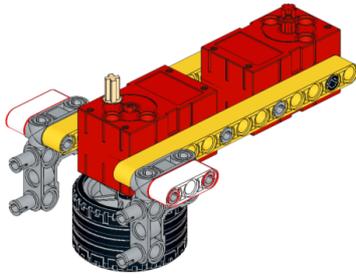
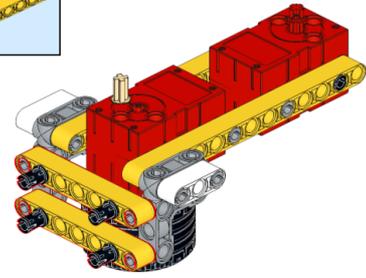
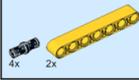
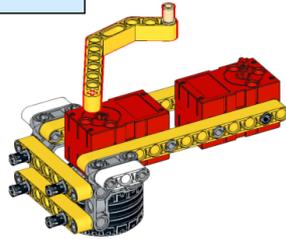
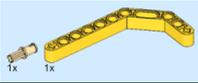
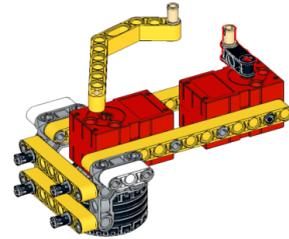
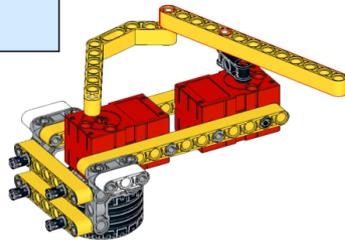
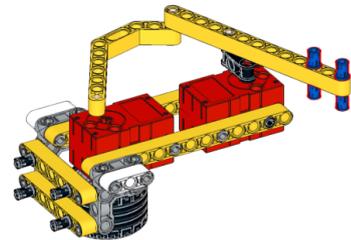


LISTA DE MATERIALES:

- Módulo de conexiones Nezha
- Placa Micro:bit
- 2 Motores
- Piezas Lego





9 10 11 12 13 14 

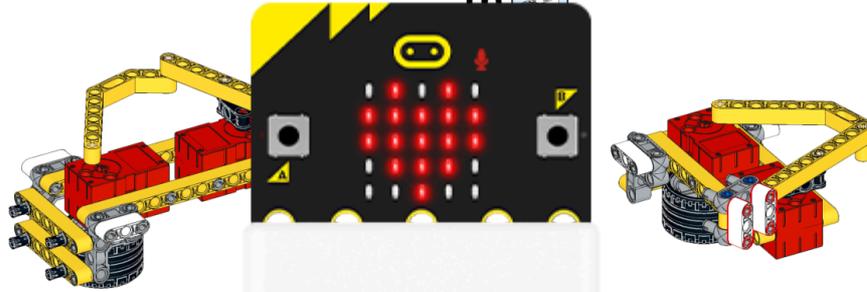
Conectar los motores y la placa microbit como se muestra en la imagen

CIRCUITO DE CONEXIONES:

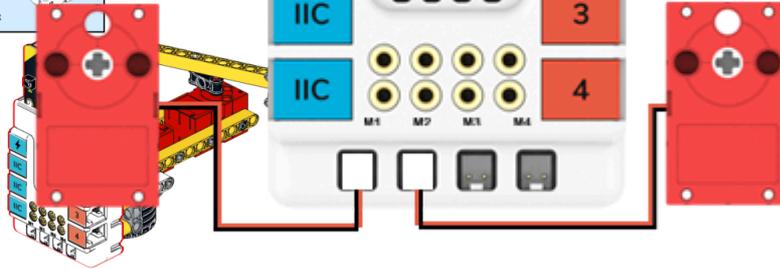
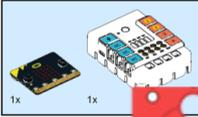
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PROGRAMACIÓN:

NEZHA V2

```
on start
  show icon [5x5 grid icon]

on button A pressed
  show icon [5x5 grid icon]
  Set motor M1 speed to 15 %
  Set motor M2 speed to 10 %

on button B pressed
  show icon [5x5 grid icon]
  Stop all motor
```