



**JULIO 2, 2024 POR MICROLOG**

# ROBOT DE ARRASTRE

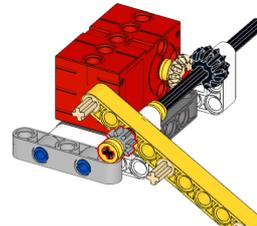
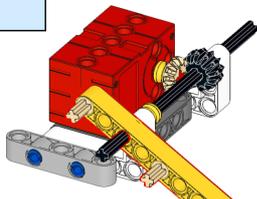
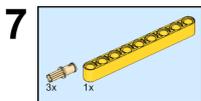
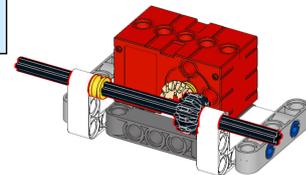
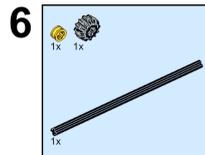
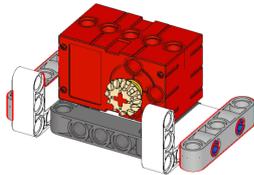
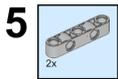
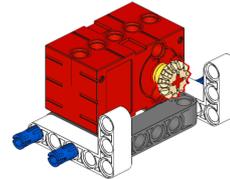
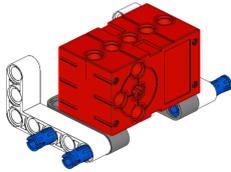
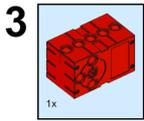
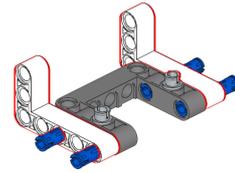
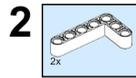
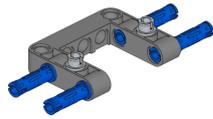
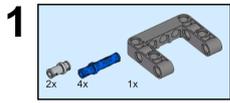
## OBJETIVO:

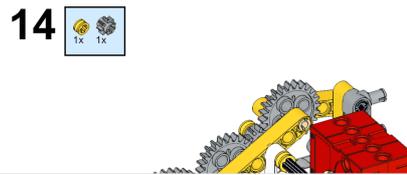
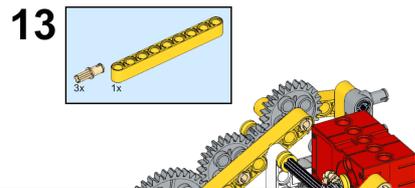
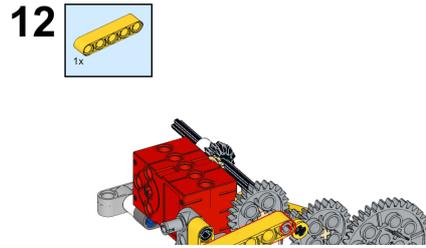
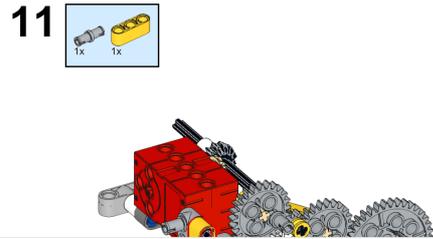
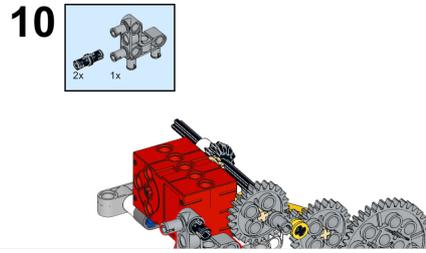
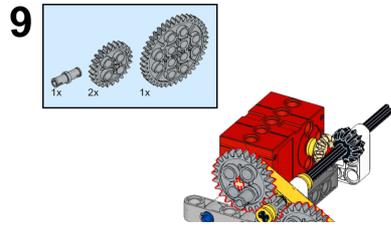
Construye un robot capaz de arrastrarse



## LISTA DE MATERIALES:

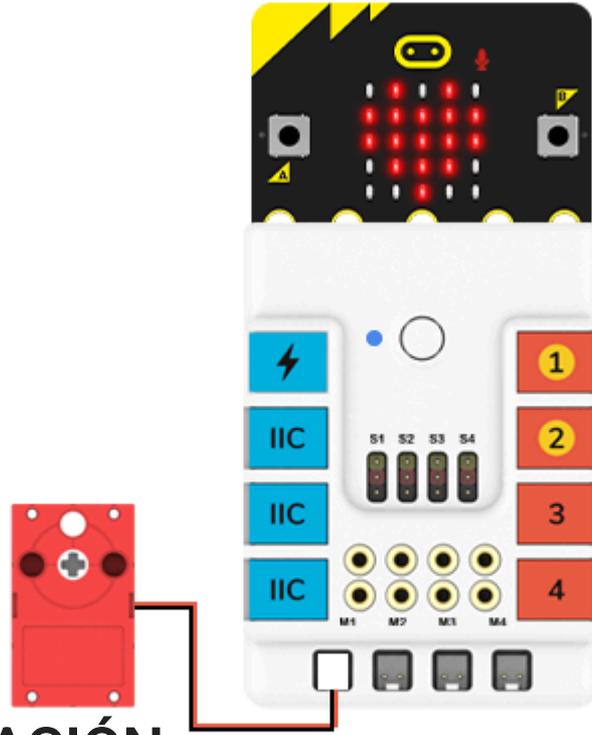






Conecta el motor y la placa microbit como se muestra en la imagen.

CIRC



PROGRAMACIÓN:

```
on button A pressed
  show icon [grid]
  Set motor M1 speed to 100 %
```

```
on button B pressed
  Stop motor M1
  show icon [grid]
```