



JULIO 1, 2024 POR MICROLOG

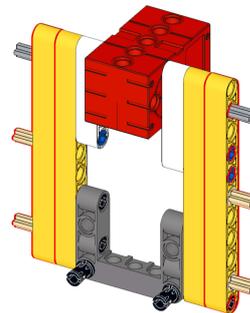
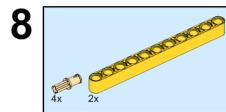
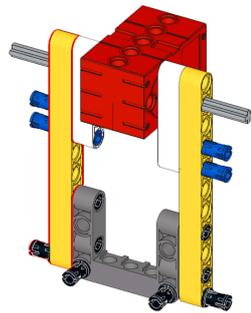
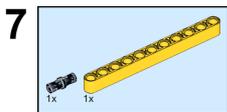
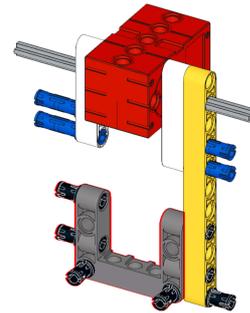
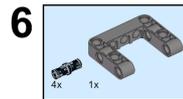
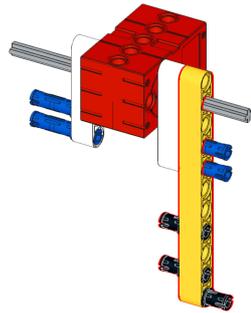
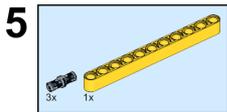
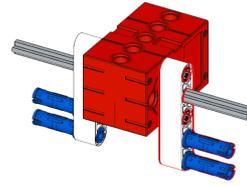
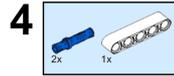
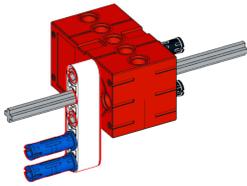
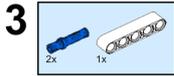
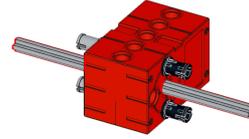
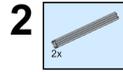
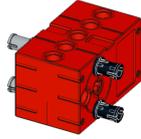
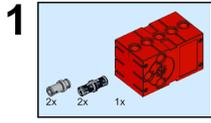
ROBOT DANZARÍN

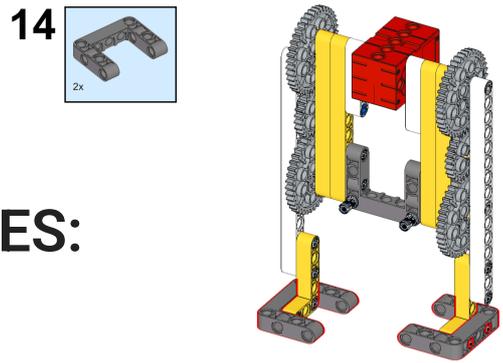
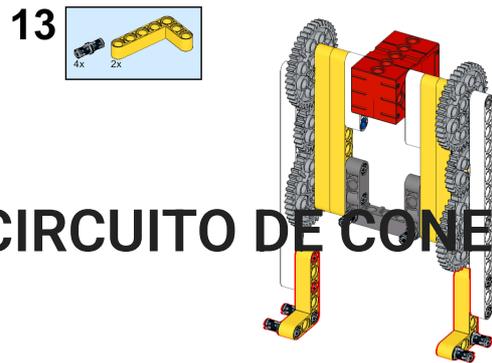
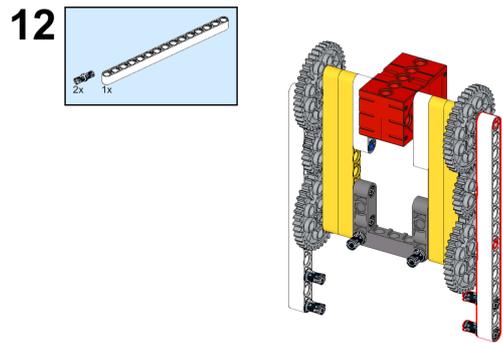
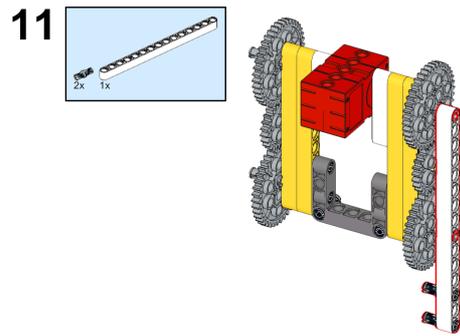
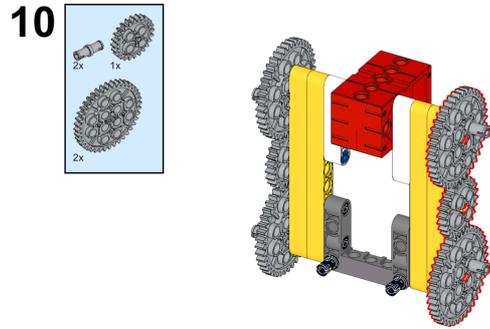
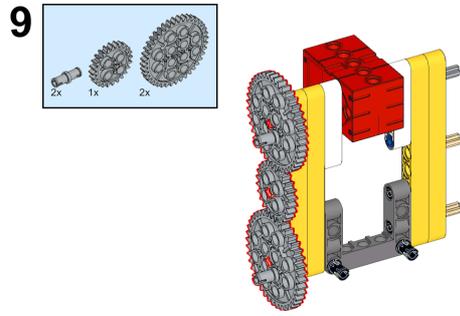
OBJETIVO:

Construye un robot que se mueve imitando una danza



LISTA DE MATERIALES:

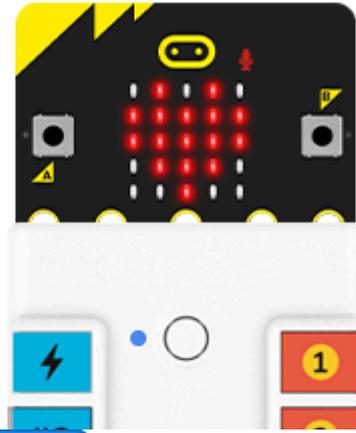




CIRCUITO DE CONEXIONES:

Conectar el motor y la placa microbit como se muestra en la imagen

15



17

```
on start
  show icon [grid icon]
```

P

```
on button A pressed
  Set motor M1 speed to -15 %
```

```
on button B pressed
  Stop motor M1
```

 **NEZHA V2**