



JULIO 1, 2024 POR MICROLOG

ROBOT ANDADOR

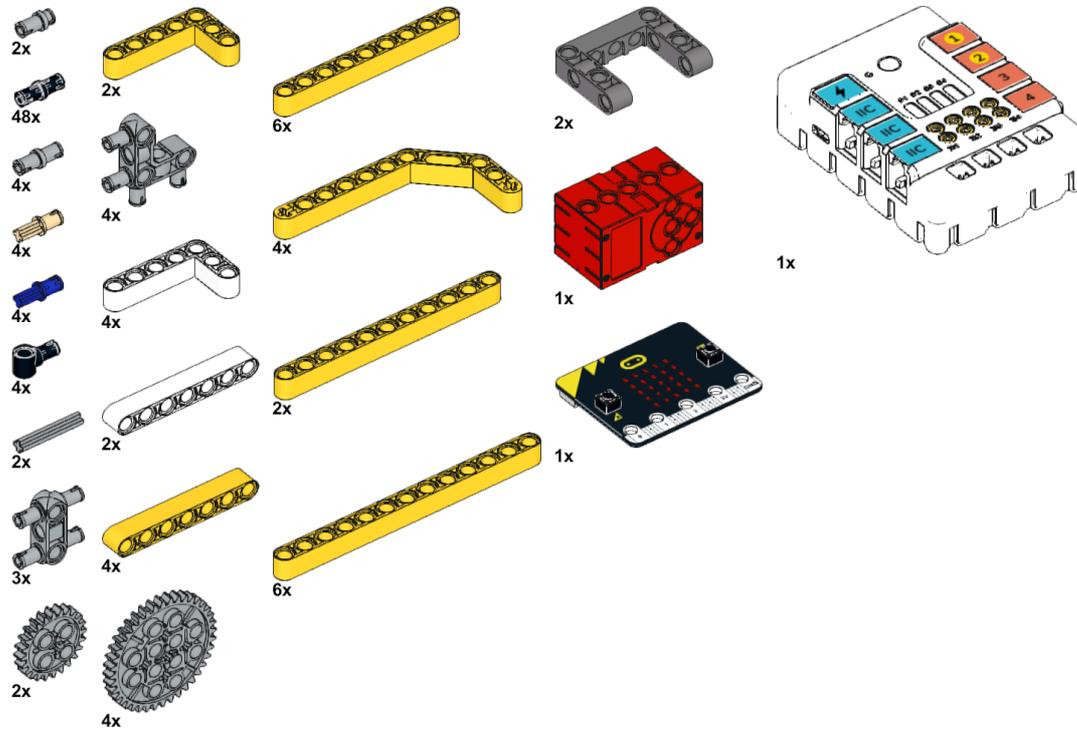
OBJETIVO:

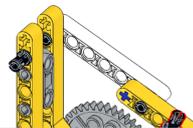
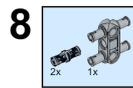
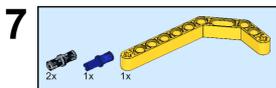
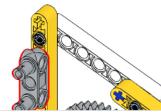
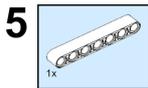
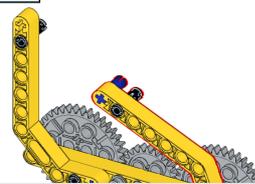
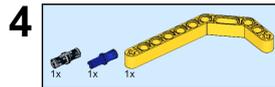
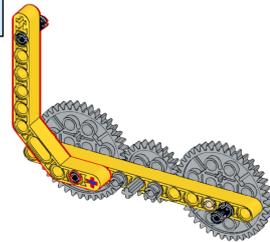
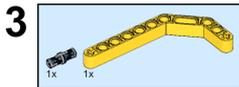
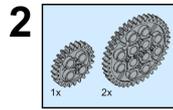
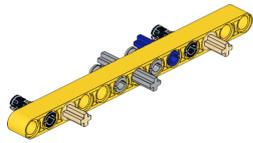
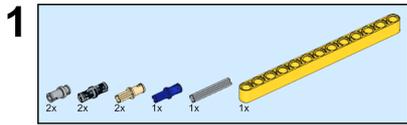
Construye un robot capaz de avanzar dando pasos



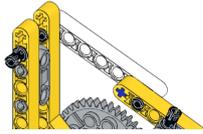
LISTA DE MATERIALES:

- Módulo de conexiones Nezha
- Placa Micro:bit
- 1 Motor
- Piezas Lego

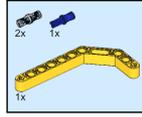




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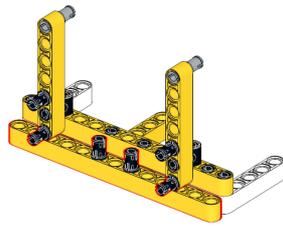
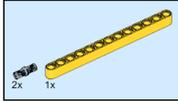
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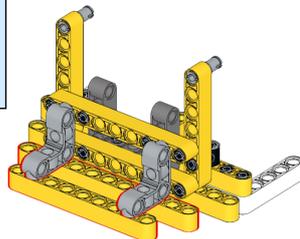
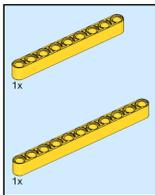
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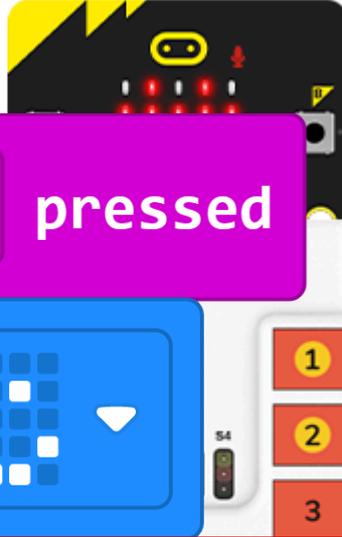
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CIRCUITO DE CONEXIONES:

Conecta el motor y la placa microbit como se muestra en la imagen.

PROGRAMACIÓN:



```
on button A pressed
  show icon [5x5 grid icon]
  Set motor M1 speed to 100 %
```

```
on button B pressed
  Stop motor M1
  show icon [5x5 grid icon]
```

NEZHA V2