



JULIO 1, 2024 POR MICROLOG

LANZADOR DE PEONZAS

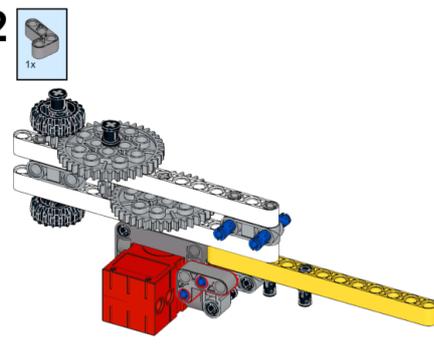
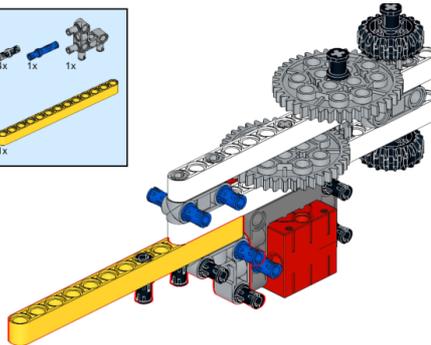
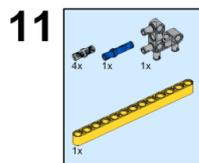
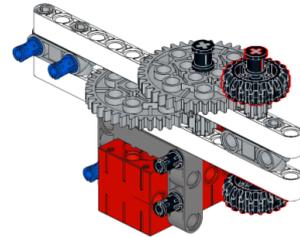
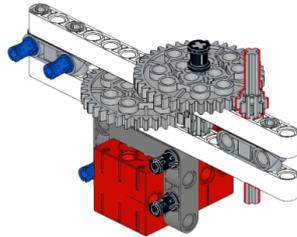
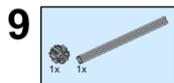
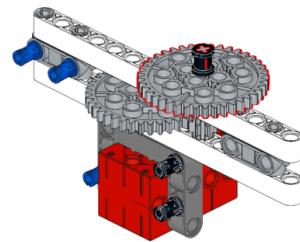
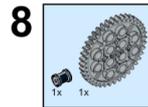
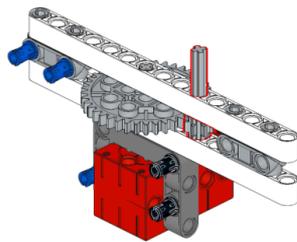
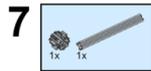
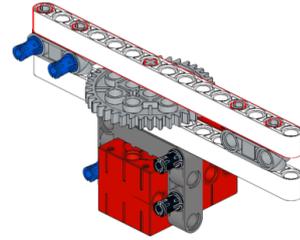
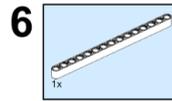
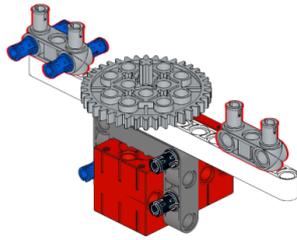
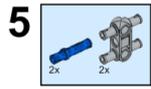
OBJETIVO:

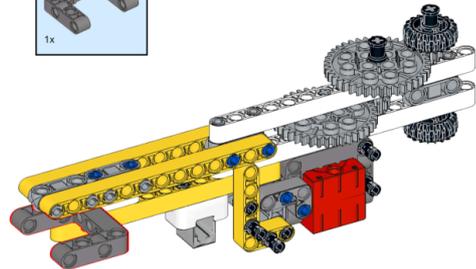
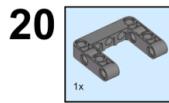
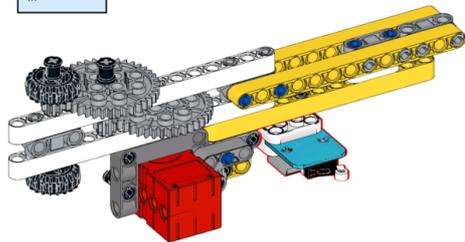
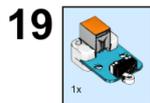
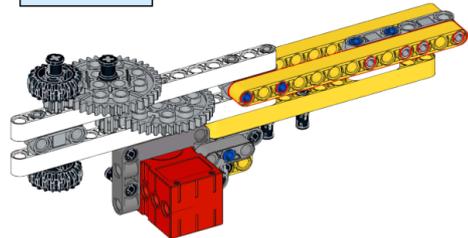
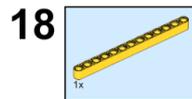
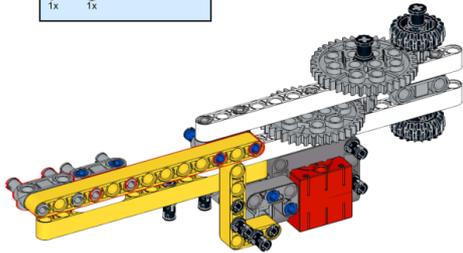
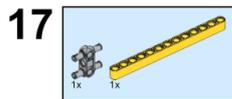
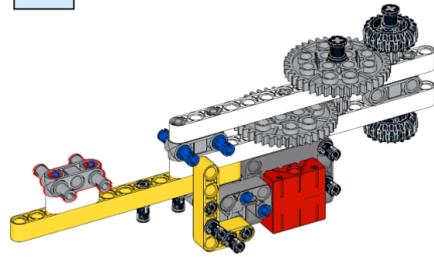
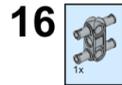
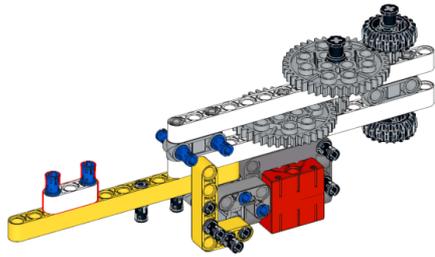
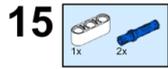
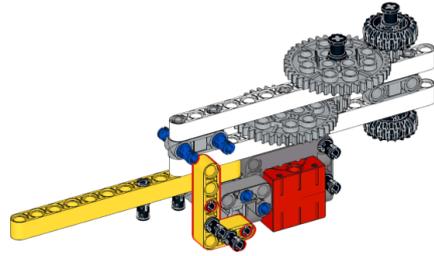
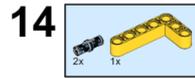
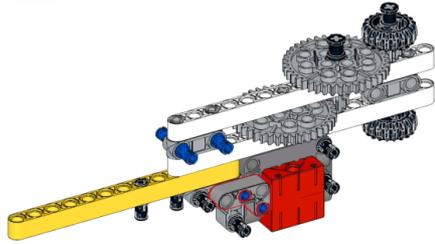
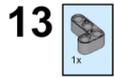
Construir un dispositivo capaz de lanzar y hacer girar peonzas.

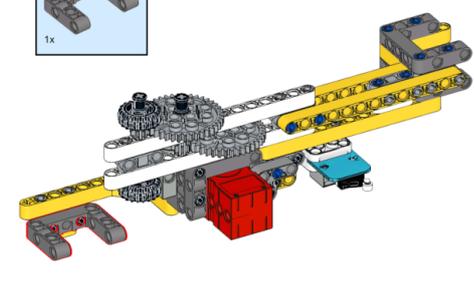
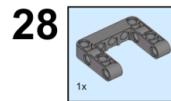
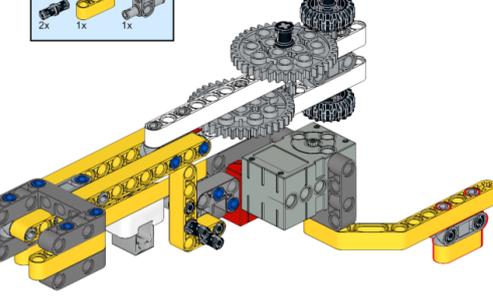
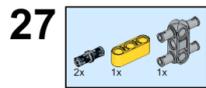
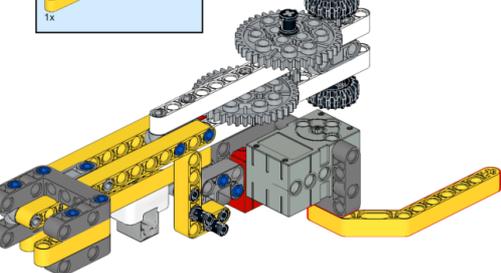
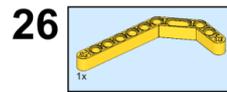
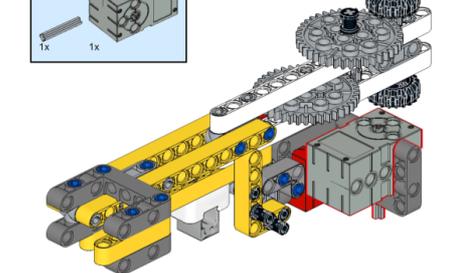
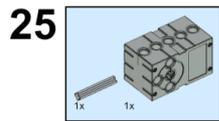
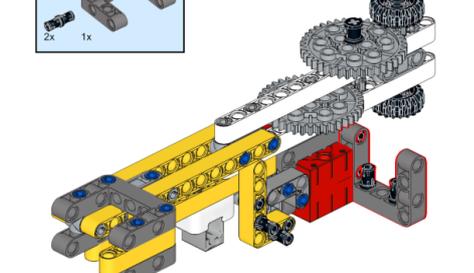
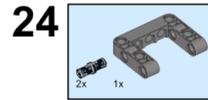
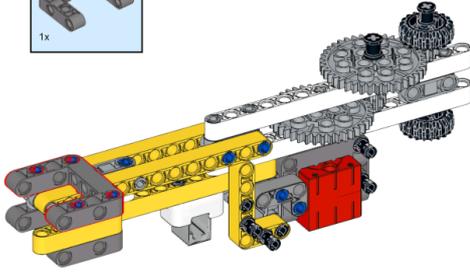
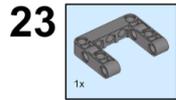
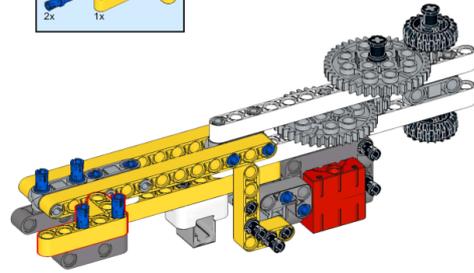
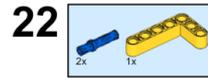
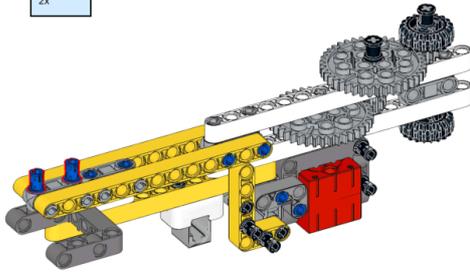


LISTA DE MATERIALES:

- Módulo de conexiones Nezha
- Placa Micro:bit



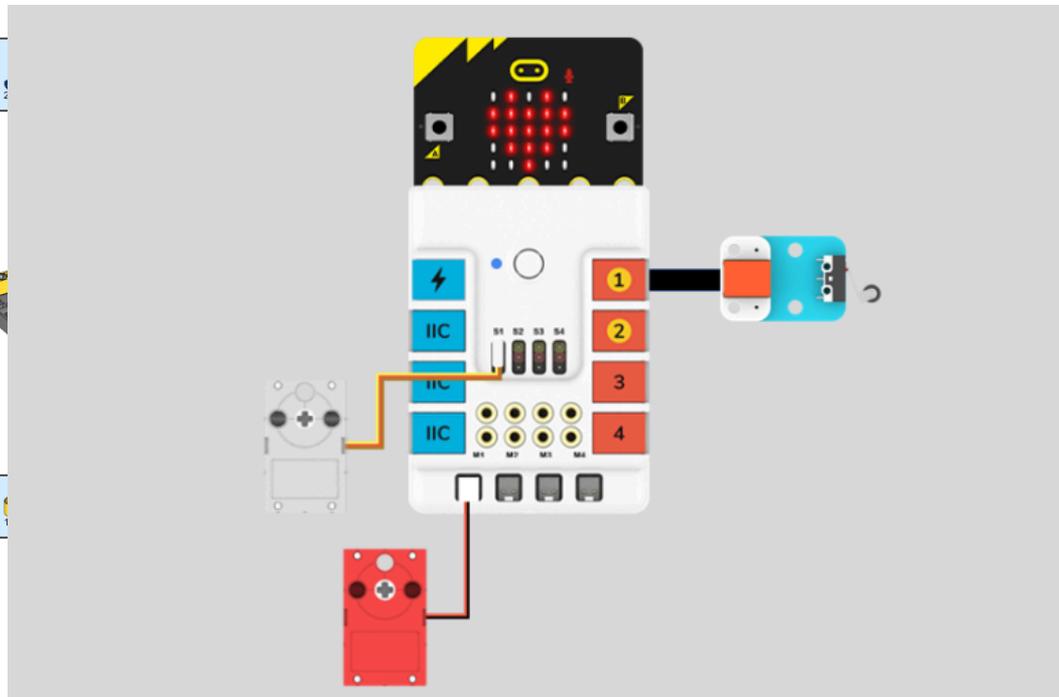




CIRCUITO DE CONEXIONES:

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PROGRAMACIÓN:



NEZHA V2

```
on_start
  Set 180° servo S1 angel to 160°

forever
  if Crash Sensor J1 is pressed then
    Set motor M1 speed to 100%
    Set 360° servo S1 angel to 210°
  else
    Stop motor M1
    Set 360° servo S1 angel to 160°
```