



JULIO 1, 2024 POR MICROLOG

DETECTOR DE OBSTÁCULOS EN UNA LÍNEA

OBJETIVO:

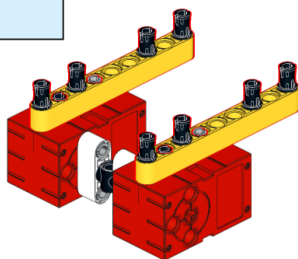
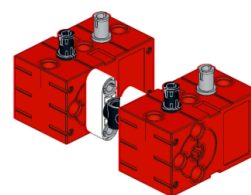
Construir un robot que sigue una línea y para cuando encuentra un obstáculo.



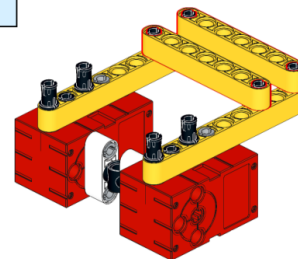
LISTA DE MATERIALES:

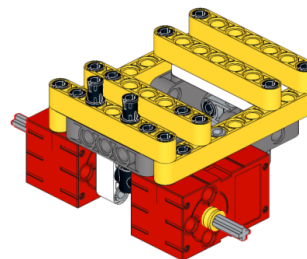
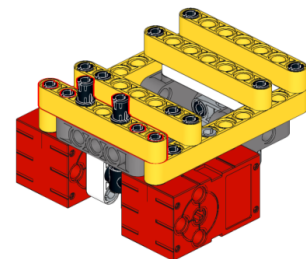
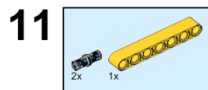
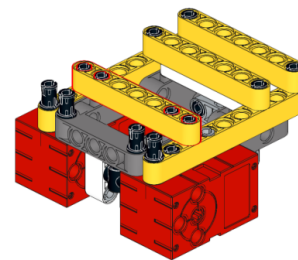
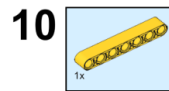
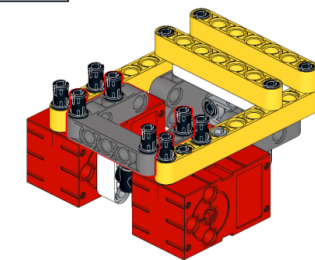
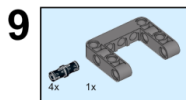
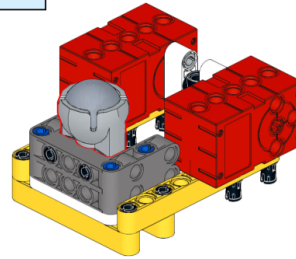
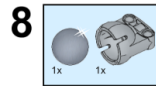
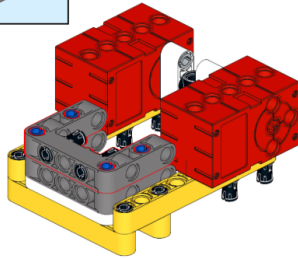
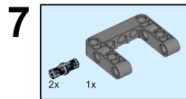
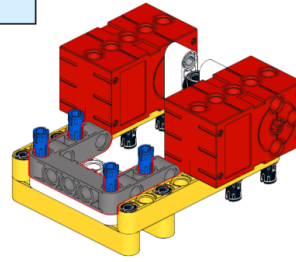
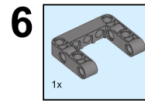
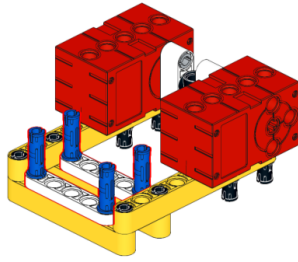
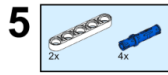
- Módulo de conexiones Nezha

- [illegible]

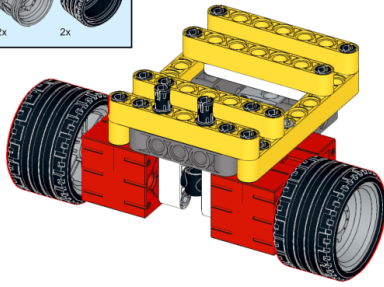
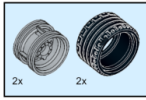


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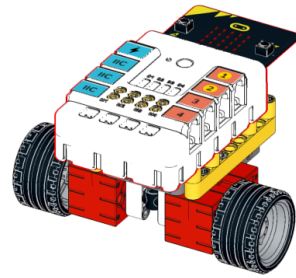
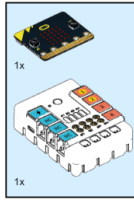




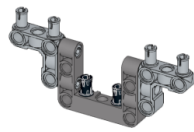
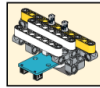
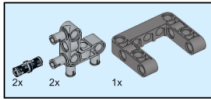
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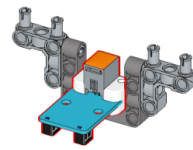
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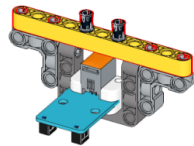
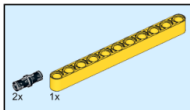
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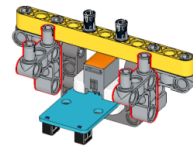
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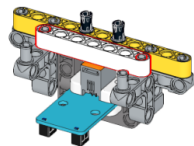
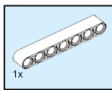
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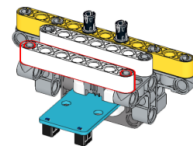
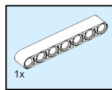
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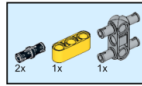


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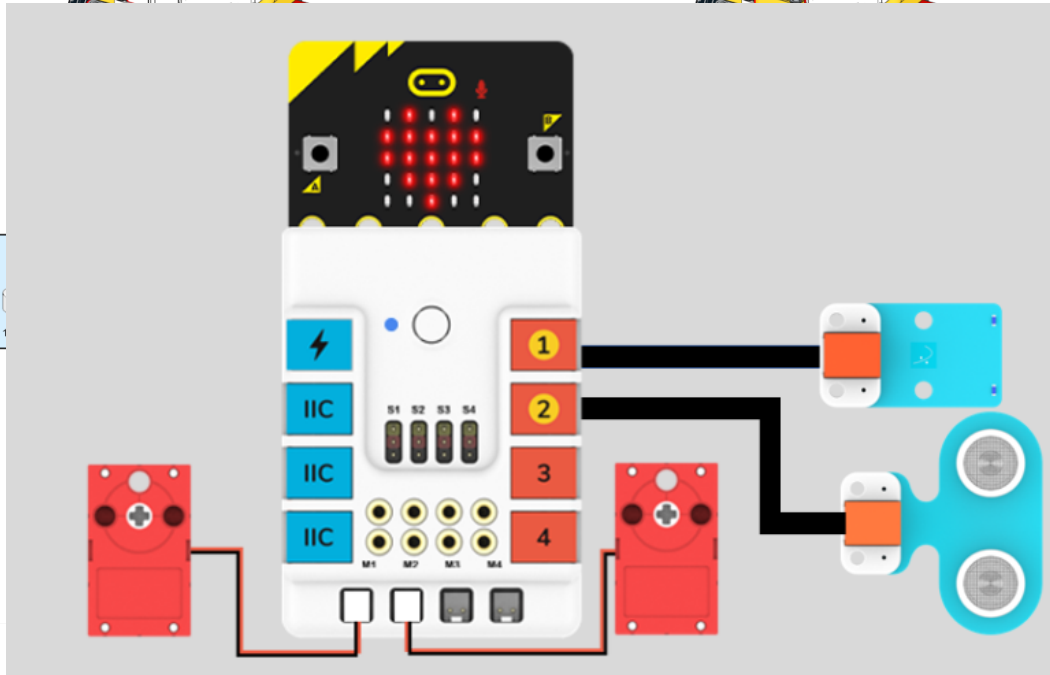
21

22



CIRCUITO DE CONEXIONES:

23



PROGRAMACIÓN:

